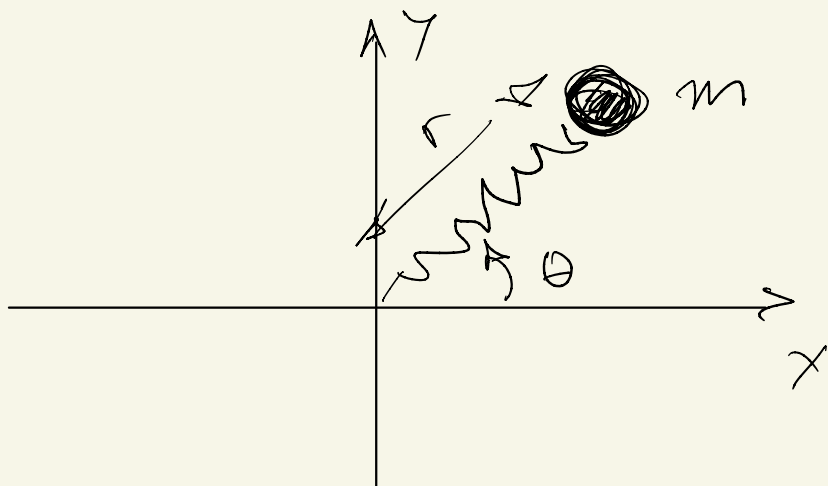


Lesson 9



$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - \frac{1}{2} k r^2$$

It is easy to see that the system is time invariant and also it does not depend on θ .

$$E = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + \frac{1}{2} k r^2$$

θ being cyclic

$$M = m r^2 \dot{\theta}$$

momentum is conserved

To calculate H we switch to
to r, p_r, θ, p_θ

$$p_\theta = m r^2 \dot{\theta} = M \quad \text{and} \quad p_r = m \dot{r}$$

$$\rightarrow H = \frac{p_r^2}{2m} + \frac{p_\theta^2}{2m r^2} + \frac{1}{2} k r^2 = E$$

Same definitions:-

Involutions

Two functions F_1 and F_2
are in involution if their
Poisson bracket is 0.

$$[F_1, F_2] = 0$$

Integrable systems

If a system with N degrees of freedom
has N conserved quantities that are in
involution then the system
is integrable

i.e.

If the conserved quantities of the system are denoted by

$$C_i = C_i(q, p)$$

$i = 1, \dots, N$, each being a function of all the $2N$ phase-space coordinates

Then the system is integrable

if

$$[C_i, C_j] = 0 \quad \forall i, j$$

Let's apply it to our example
We can think that the C_i s are H and p_θ for example.
These are 2 quantities that are conserved.

We calculate the Poisson brackets

$$[H, p_\theta] = \frac{\partial H}{\partial r} \frac{\partial p_\theta}{\partial p_r} - \frac{\partial H}{\partial p_r} \frac{\partial p_\theta}{\partial r} + \frac{\partial H}{\partial \theta} \frac{\partial p_\theta}{\partial p_\theta} - \frac{\partial H}{\partial p_\theta} \frac{\partial p_\theta}{\partial \theta} =$$

$$[H, p_\theta] = 0$$

(all terms above are 0)

and if we calculate

$$[H, H] = 0 \quad \text{and} \quad [p_\theta, p_\theta] = 0$$

Our system is then integrable

Let's find $r(t)$, $p_r(t)$, $\theta(t)$ and $p_\theta(t)$

Hamilton eqs are

$$\left[\begin{aligned} \dot{\theta} &= \frac{\partial H}{\partial p_\theta} = \frac{p_\theta}{mr^2} \\ \dot{p}_\theta &= -\frac{\partial H}{\partial \theta} = 0 \\ p_\theta &= \text{constant} \end{aligned} \right]$$

$$\text{then } \frac{d\theta}{dt} = \frac{p_\theta}{mr^2} \rightarrow d\theta = \int \frac{p_\theta}{mr^2} dt$$

$$\text{and } \dot{r} = \frac{\partial H}{\partial p_r} \quad \dot{p}_r = -\frac{\partial H}{\partial r}$$

$$\rightarrow \dot{r} = \frac{pr}{m} \quad \text{used}$$

$$p_r = + \frac{p_\theta^2}{m r^3} - \kappa r$$

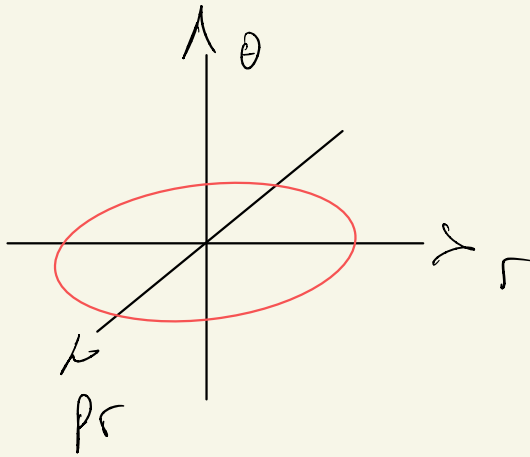
From H \rightarrow

$$p_r = \sqrt{2m \left(E - \frac{p_\theta^2}{2m r^2} - \frac{1}{2} \kappa r^2 \right)}$$

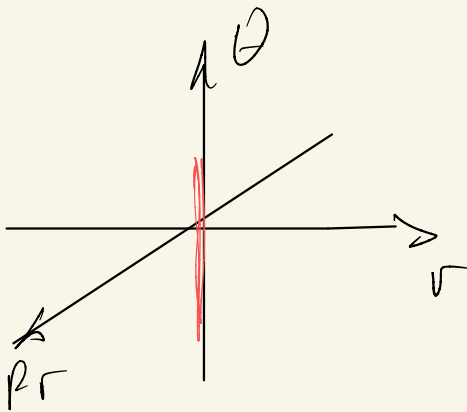
$$\frac{m r \, dr}{\sqrt{2 E m r^2 - p_\theta^2 - \kappa m r^4}} = \int dt = t$$

$$\int dr p_r = p_r = \int \left(\frac{p_\theta^2}{m r^3} - \kappa r \right) dt$$

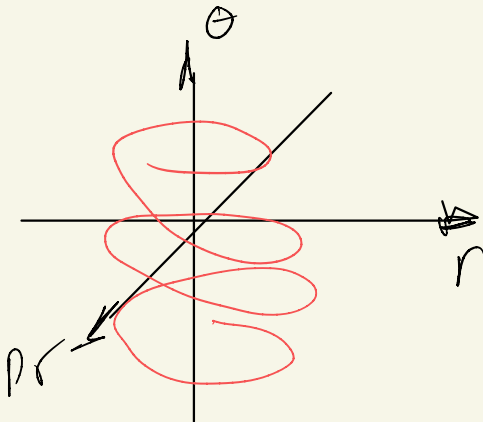
A look into phase space



a) trajectory with
 $p_\theta = 0$
 $\theta = \text{constant}$

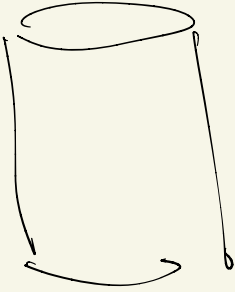


b) trajectory
 with $\ddot{\theta} = \sqrt{\frac{k}{m}}$
 $\ddot{\theta} = 0!$
 ($r = \text{constant}$)
 then $p_r = 0$



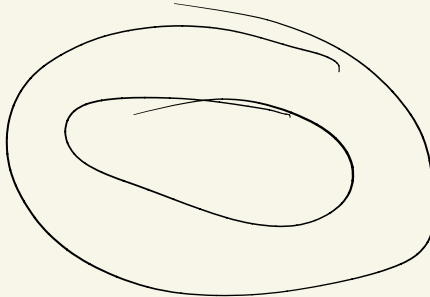
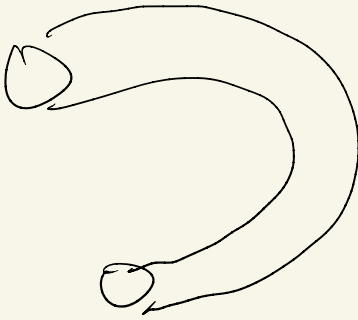
c) A generic
 trajectory

Notice that motion
occurs on the surface of a
cylinder.



but because

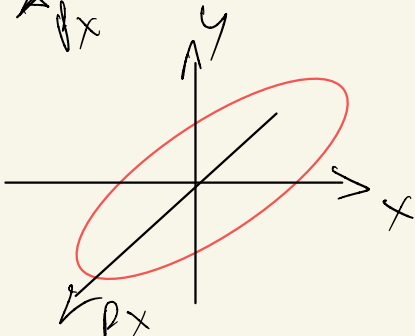
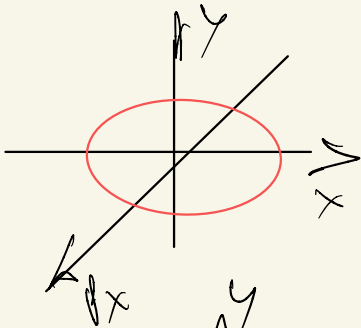
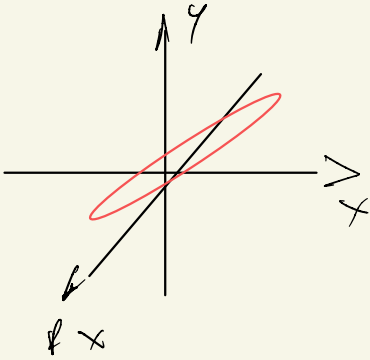
$$\theta = 0 \rightarrow \theta = 2\pi$$



torus

Let's look at the same problem in Cartesian coordinates.

$$H = \frac{p_x^2}{2m} + \frac{1}{2} k x^2 + \frac{p_y^2}{2m} + \frac{1}{2} k y^2$$



We can imagine now

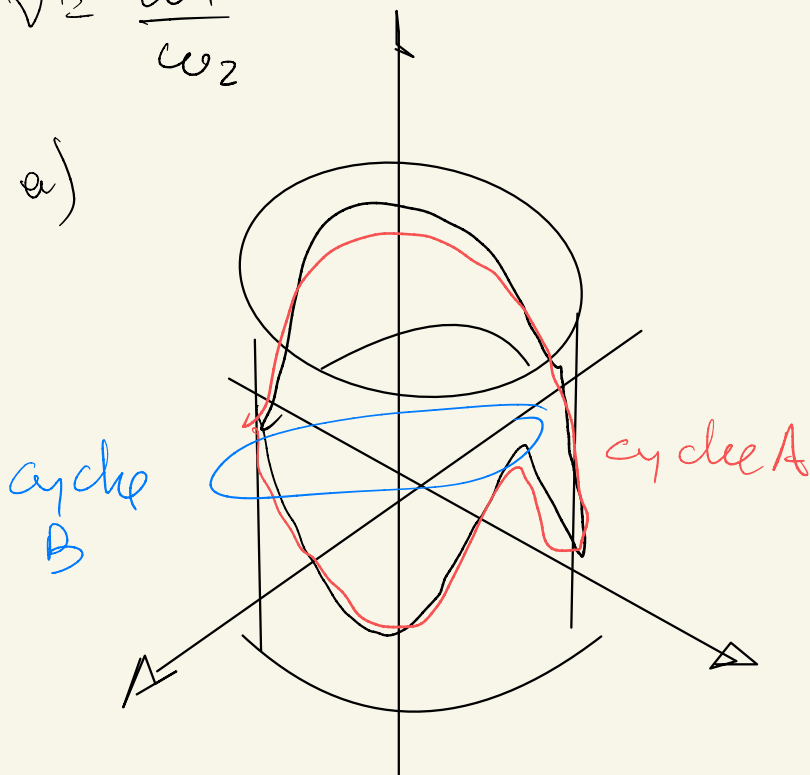
$$H = \frac{p_x^2}{2m} + \frac{1}{2} m \omega_1^2 x^2 + \frac{p_y^2}{2m} + \frac{1}{2} m \omega_2^2 y^2$$

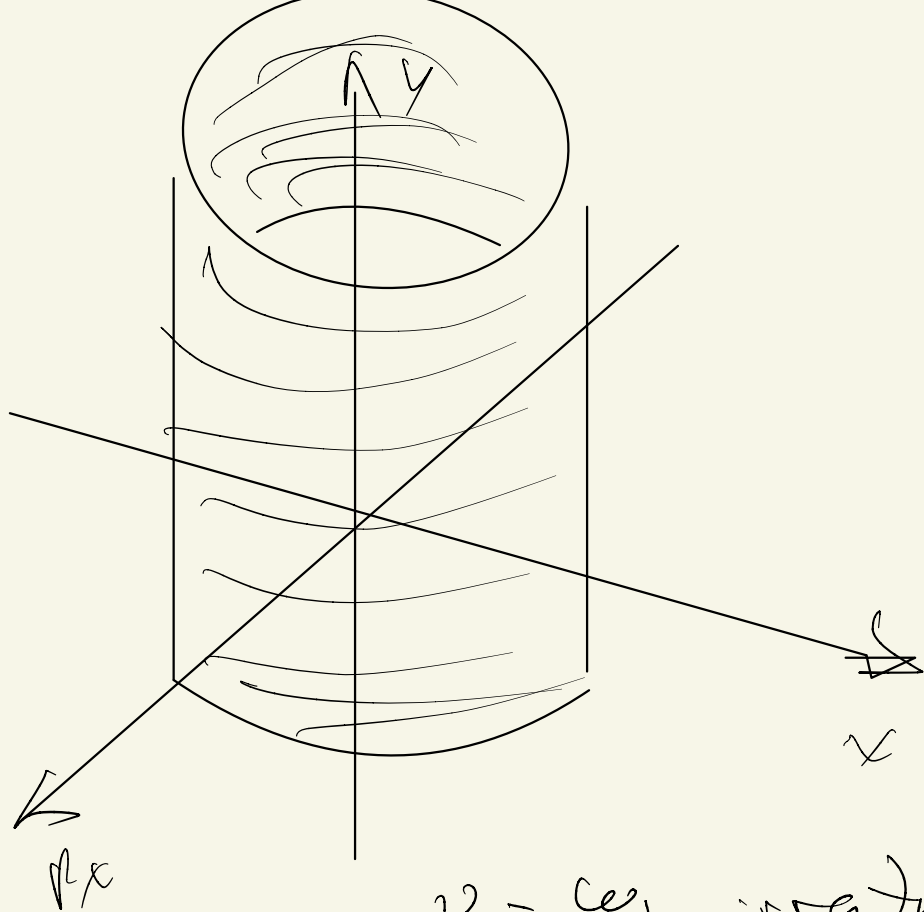
with $\omega_1 \neq \omega_2$

The energy of each oscillator (how there are 2!) is conserved, and they are in involution.

$$\nu = \frac{\omega_1}{\omega_2}$$

a)





$$v = \frac{c v_1}{\omega_2} \text{ irrational}$$

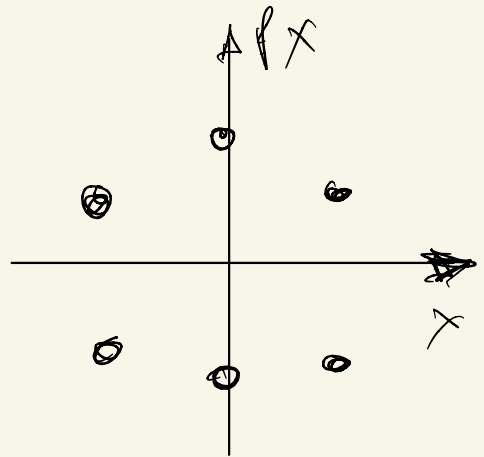
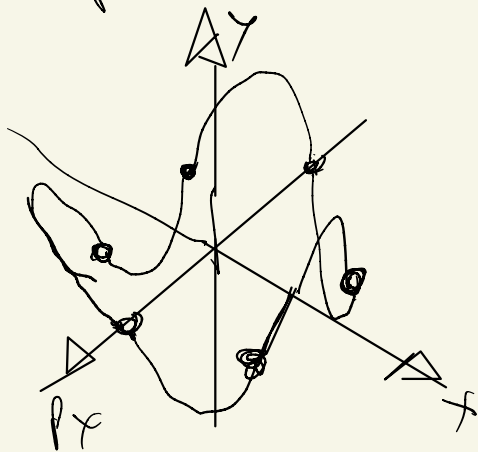
The outer sections of the
 N -subspaces defined by $C_i = C_i(\gamma, p)$
 is a torus in a $2N-N$
 $= N$ dimensional space.
 \pm can be identified as
 a hypercube with opposing

ends identified.

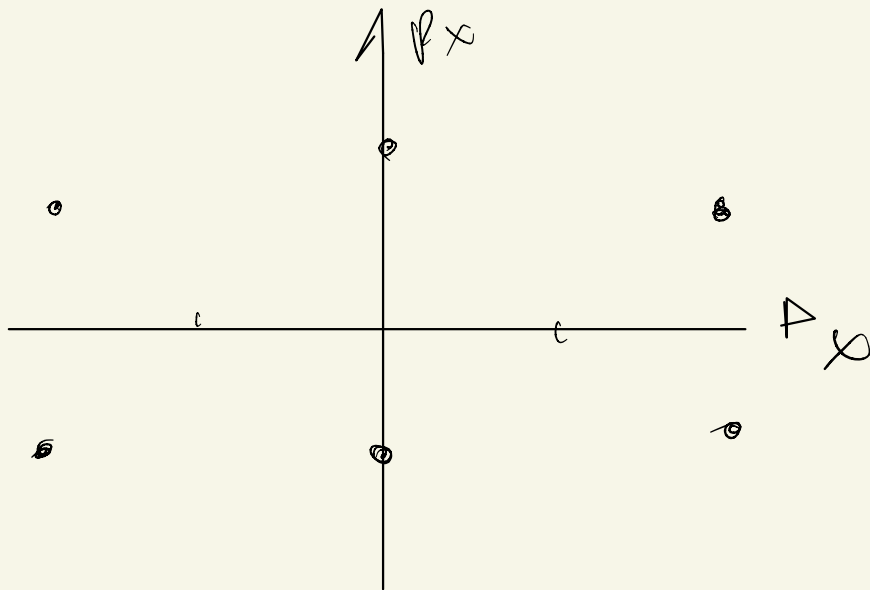
For an integrable system in 2-~~D~~ phase space, the trajectory is confined to the surface of an N dimensional torus.

Non integrable systems

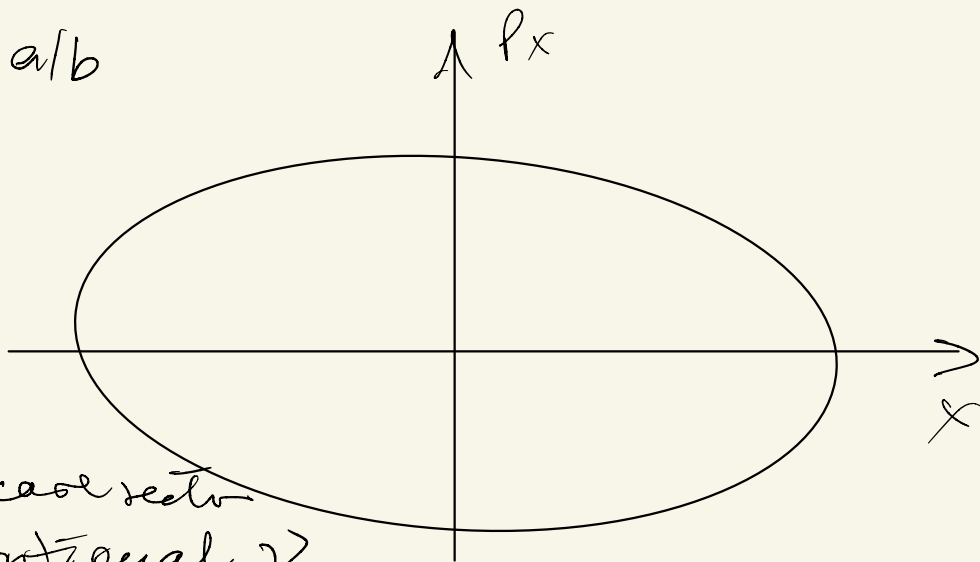
Let's look at 2-D snap shots.
going back to the 2-D oscillator



We can read v from the number of times it circles the central point



Poincaré section for a rational $v = a/b$



Poincaré section
for rational v

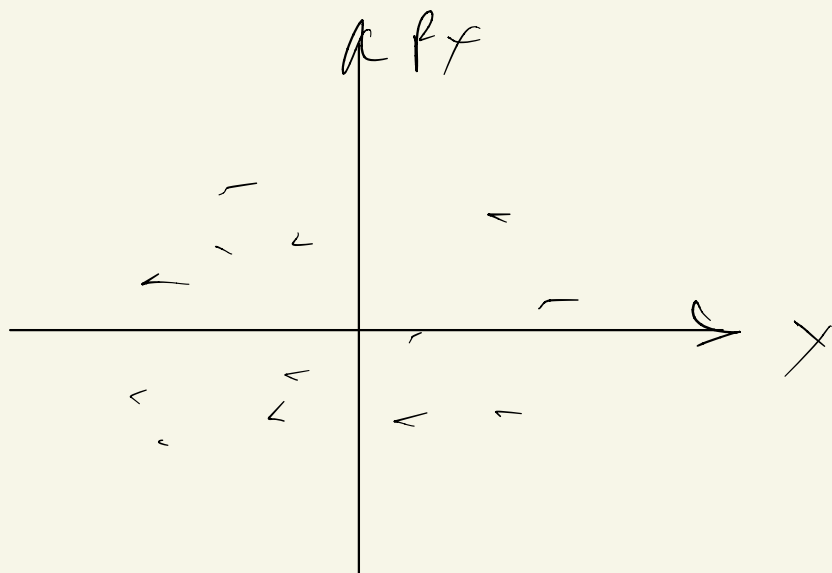
These curves are called
KAM tori

(Kolmogorov, Arnold and Moser)

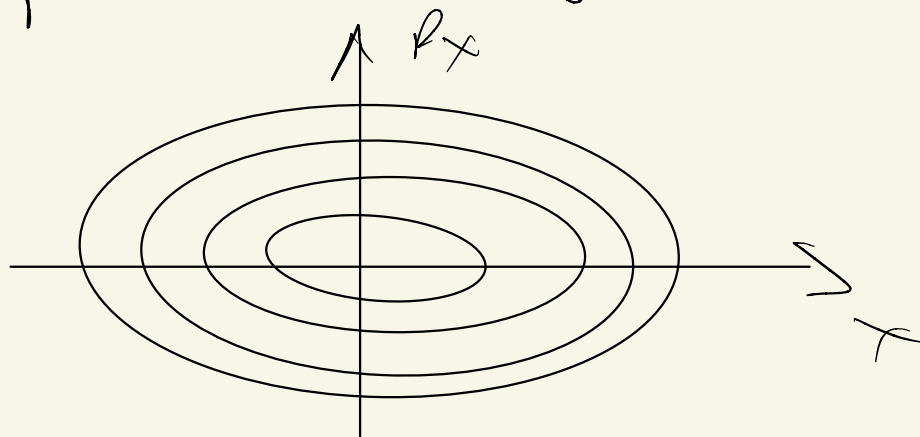
The 2 dimensional maps are
called Poincaré sections
(or maps)

For integrable \Rightarrow systems

Poincaré sections consist
of a collection of closed loops
and discrete points when
we go over different initial
conditions.



Poinsone sections w/ rational
 winding numbers for various
 initial conditions depending
 on different total energies.




Consider a setup w/
 2 equal frequency harmonic
 oscillators coupled to each
 other.

$$H = \frac{p_1^2}{2m} + \frac{1}{2} m \Omega^2 q_1^2 + \frac{p_2^2}{2m} + \frac{1}{2} m \Omega^2 q_2^2 \\
+ \frac{1}{2} m^{3/2} q_1 q_2^2 - \frac{1}{6 m^{3/2}} q_1^3$$

This is the Henon - Heiles
 system. (2-D potential)

It was thought to model the
 dynamics of a star in the
 axisymmetric potential of
 a galaxy (q_1 the radial
 location of the star from the
 center of the galaxy and
 q_2 the angle of declination).

If we flip the sign for the last term.

$$H = \frac{p_1^2}{2m} + \frac{1}{2} m \omega^2 q_1^2 + \frac{p_2^2}{2m} + \frac{1}{2} m \omega^2 q_2^2 \\ + \frac{1}{2m^{3/2}} q_1 q_2^2 + \frac{1}{6m^{3/2}} q_1^3$$


this system is integrable
(not obvious)

If our goal is to analyse what happens as an integrable system turns into a chaotic one.

One technique \rightarrow Henon - Heiles
 \rightarrow non linear term right away

Another technique is to introduce the perturbation gradually
conservative chaos: the Hamiltonian is independent of time.
If we add dissipation & time dissipative chaos!

Conservative ~~conservative~~ class

same system \rightarrow before
but with rest length of
spring r_0 (instead of 0)
and with gravity

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - \frac{1}{2} k (r - r_0)^2 + m g r \cos \theta$$

Energy

$$E = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + \frac{1}{2} k (r - r_0)^2 - m g r \cos \theta$$

E is ~~constant~~

Angular momentum is conserved

We have 1 conserved quantity now
for a 2 DOF system.

Let's solve the equations
numerically

A natural scale is given by r_0

$$R = \frac{r}{r_0}$$

also we can define $T = \sqrt{\frac{k}{m}} t$

T is the # of oscillations periods

$$\text{So } d/dt \rightarrow \frac{d}{dT} = \sqrt{\frac{k}{m}} \frac{d}{dT}$$

$L \rightarrow$ in terms of R and T

$$L = \frac{1}{2} (\dot{R}^2 + R^2 \dot{\theta}^2) - \frac{1}{2} (R-1)^2$$

$$+ \epsilon R \cos \theta$$

$$\text{and } \epsilon \equiv \frac{mg}{kr_0}$$

Let's start with $\epsilon = 0$

Assume $\epsilon \ll 1$

R near eq. is $R_{eq} = 1 + \epsilon$

$$R = R_{eq} + x = 1 + \epsilon + x$$

$$\cos \theta \approx 1 - \frac{\theta^2}{2}$$

$$x \ll R_{eq} \quad \theta \ll 1$$

$$L = \frac{1}{2} \dot{x}^2 - \frac{1}{2} x^2 + \frac{1}{2} (1 + \epsilon)^2 \dot{\theta}^2 - \frac{1}{2} \epsilon (1 + \epsilon) \theta^2$$

This is equivalent to 2 harmonic oscillators & 2 angular frequencies

$$\omega_x = 1 \quad \omega_\theta = \sqrt{\frac{\epsilon}{1 + \epsilon}}$$

Under this binomial section would be KAM tori

The winding number is

$$\nu \equiv \frac{\omega_\theta}{\omega_x} = \sqrt{\frac{\varepsilon}{1+\varepsilon}}$$

in general irrational (except
for special values of ε)

small $x, \theta \rightarrow x \neq \theta$ stay small

If we look beyond this

For small but fixed perturbation
 ε , the winding #s of KAM tori
for different initial conditions
become functions of the initial
conditions as in figure (see photo)

At the center is a single
point KAM torus of $\nu=1$

For $\theta \neq 0$ this corresponds
to stable vertical oscillations

at fixed $\theta = 0$

These points in Poincaré sections are stable tori (fixed points or elliptic points)

KAM theorem

The theorem is concerned with the stability of motions in hamiltonian systems, that are small perturbations of integrable hamiltonian systems.

If a small perturbation is added to an integrable system, initial conditions corresponding to irrational KAM tori in Poincaré sections are affected by minimal deformations with dynamics non chaotic

However tori with rational winding numbers are expected to disintegrate into chaotic motion.

Are irrational #s more or less irrational?

Dirichlet's theorem

(Approximation theorem or Diophantine approximation)

For any real number α and N with $1 \leq N$ there are integers p and q such $1 \leq q \leq N$ and

$$|q\alpha - p| \leq \frac{1}{LN+1} < \frac{1}{N}$$

where $LN+1$ is the integer part of N .

For example

$$\nu = c_1 + \frac{1}{c_2 + \frac{1}{c_3 + \frac{1}{c_4 + \dots}}}$$

c_i 's are unique integers.

The more c_i 's we used to approximate ν (for a required precision) the "loss rational" is ν .

The most "irrational" number corresponds to the minimum value for the c_i 's, i.e. $c_i = 1$ which is

$$\nu = \sqrt{5-1} / 2 \approx 0.618033988$$

which is the inverse of the golden ratio.

Inductively rational
winding #s are a
sequence of disconnected
dots that will form
scatter around and destroy
the tori

irrational #s on the other
hand, diffuse the effect of
the perturbations leading
to stable tori

Most initial conditions
correspond to stable KAM tori
(most #s between 0 and 1 are
irrational)

we can define chaos
as the absence of integrability

But for different initial
conditions, we may encounter
regions of stability - particularly
when the non-integrable nonlinearities
are small.

regions of chaos and regions of
~~KA~~ stability.

Quantifiable new definition
of chaos.

i.e. we shift a given set of
initial conditions by a fixed
amount and compute the
distance d between
2 trajectories

$$d^2(t) = \sum_i (q_i^1(t) - q_i(t))^2$$

q to shifted q^1

If we found that at long times we have

$$d(t) \propto e^{\lambda t}$$

with $\lambda > 0$ we say that the corresponding initial conditions lead to chaotic evolution.

λ Lyapunov exponent
then regions of chaos in a
Poincaré section can be labeled
by Lyapunov exponents

if instead $\lambda \leq 0$ attractor behavior
dynamics attracted to a stable
torus in phase space.

Ergodicity

Evolution of a system in phase space is said to be ergodic if given enough time, the trajectory of the system comes arbitrarily close to any point in phase space.

chaos \rightarrow implies \rightarrow ergodicity.